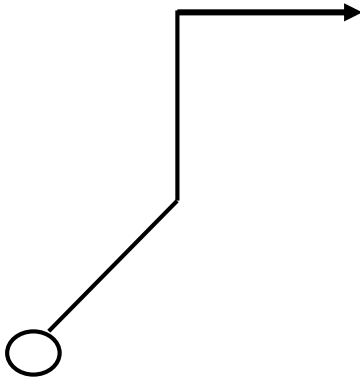
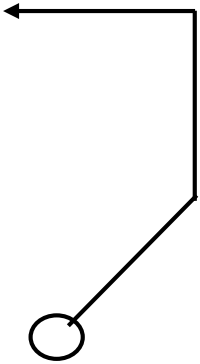


Program your robot to go out for a pass using the following patterns. Your robot should start where the circle is and finish at the arrow head on the yard line indicated for the pattern.

40 yard dig



50 Yard out



70 Yard Come Back

